



# &FAPPLE

- 1.ARSPD\_TYPE = 1
- 2.ARSPD\_OPTIONS = 15 ( DisableVoltageCorrection)
- 3.ARSPD\_AUTOCAL = 1
- 4.ARSPD\_SKIP\_CAL = 1

, , ARSPD\_OFFSET 0, 0 Fapple ARSPD\_SKIP\_CAL 1

RTL Loiter 5 ( 2 ARSPD\_RATIO) OSD

( ) ARSPD\_AUTOCAL = 0 ARSPD\_RATIO ARSPD\_RATIO=2.0,

ARSPD\_USE=1 2 ARSPD\_USE 2 0 ARSPD\_USE (AUTO,CRUISE,FBWB,RTL)

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AIRSPD\_CRUISE: ( : / M/s ) (Ardupilot4.5 TRIM\_ARSPD\_CM, /s)

AIRSPD\_MIN: ( ) 20% ( : / M/s)(Ardupilot4.5 ARSPD\_FWB\_MIN)

AIRSPD\_MAX: ( ) ARSPD\_FWB\_MIN 50% ( : / M/s)(Ardupilot4.5 ARSPD\_FWB\_MAX)

Revision #1

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